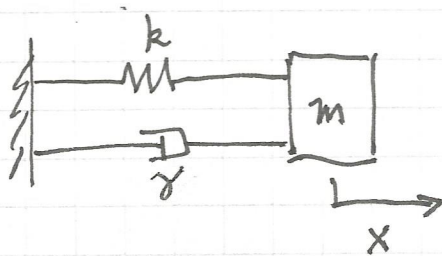
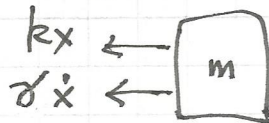


# FREE VIBRATIONS



Free body diagram



$$F = ma \Rightarrow m\ddot{x} = -kx - \gamma\dot{x}$$

$$m\ddot{x} + \gamma\dot{x} + kx = 0$$

$$x = e^{rt}$$

$$mr^2 + \gamma r + k = 0$$

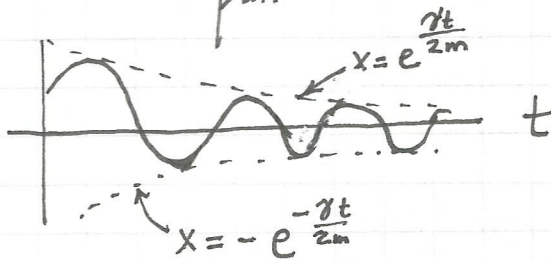
$$r = \frac{-\gamma \pm \sqrt{\gamma^2 - 4mk}}{2m}$$

The form of the solution depends on the sign of  $\gamma^2 - 4mk$

overdamped  $\gamma^2 - 4mk > 0 \Rightarrow 2$  real roots,  $x = c_1 e^{r_1 t} + c_2 e^{r_2 t}$

critically damped  $\gamma^2 - 4mk = 0 \Rightarrow$  double root,  $x = (c_1 + c_2 t) e^{-\frac{\gamma}{2m} t}$

under-damped  $\gamma^2 - 4mk < 0 \Rightarrow$  complex conjugate pair,  $x = e^{-\frac{\gamma t}{2m}} (c_1 \sin \omega t + c_2 \cos \omega t)$



$$\omega = \frac{\sqrt{4mk - \gamma^2}}{2m}$$

$$A \cos \omega t + B \sin \omega t = R \cos(\omega t - \theta)$$

$$\cos(\omega t - \theta) = \cos \omega t \cos \theta + \sin \omega t \sin \theta$$

$$\therefore A = R \cos \theta$$

$$B = R \sin \theta$$

$$A^2 + B^2 = R^2 \text{ since } \cos^2 \theta + \sin^2 \theta = 1$$

$$R = \sqrt{A^2 + B^2}$$

$$\tan \theta = \frac{B}{A}$$

$$\theta = \arctan \frac{B}{A}$$

Example

$$\cos t + 2 \sin t = R \cos(t - \theta)$$

$$R = \sqrt{1 + 4} = \sqrt{5}$$

$$\theta = \arctan 2$$

$$m u'' + \gamma u' + k u = F_0 \cos \omega t$$

$$u_p = A \cos \omega t + B \sin \omega t$$

$$u_p' = -A \omega \sin \omega t + B \omega \cos \omega t$$

$$u_p'' = -A \omega^2 \cos \omega t - B \omega^2 \sin \omega t$$

$$m(-A \omega^2 \cos \omega t - B \omega^2 \sin \omega t)$$

$$+ \gamma(-A \omega \sin \omega t + B \omega \cos \omega t)$$

$$+ k(A \cos \omega t + B \sin \omega t) = F_0 \cos \omega t$$

Collect terms:

$$(1) \quad \cos \omega t: -A \omega^2 m + B \omega \gamma + A k = F_0$$

$$(2) \quad \sin \omega t: -B \omega^2 m - A \omega \gamma + B k = 0$$

Multiply (1) by A, (2) by B, and add:

$$(3) \quad -R^2 \omega^2 m + R^2 k = A F_0$$

Multiply (1) by B, (2) by A, and subtract:

$$(4) \quad R^2 \omega \gamma = B F_0$$

Square eq.(3) and add to the square of eq.(4):

$$R^4 \left( (k - \omega^2 m)^2 + \omega^2 \gamma^2 \right) = R^2 F_0^2$$

or, cancelling an  $R^2$  and taking the square root:

$$R = \frac{F_0}{\Delta}, \quad \Delta = \sqrt{(k - \omega^2 m)^2 + \omega^2 \gamma^2}$$

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Thus we have shown that the  
"steady state" solution of

$$m u'' + \gamma u' + k u = F_0 \cos \omega t$$

is  $u = R \cos(\omega t - \theta)$

where  $R = \frac{F_0}{\Delta}$

where  $\Delta = \sqrt{(k - \omega^2 m)^2 + \omega^2 \gamma^2}$

Note: "steady state" means the  
solution after the homogeneous solution  
has decayed to zero.